

Solutions to HW4

$$1. a) (\theta, v) = (\bar{\theta}, \bar{v}) \Rightarrow \bar{v} = 0 \Rightarrow \sin \bar{\theta} = 0$$

$$-r\bar{v} - \sin \bar{\theta} = 0 \Rightarrow \theta = 0, \pi$$

$$b) \begin{cases} \dot{F} = v \\ \dot{g} = -r v - \sin \theta \end{cases} \Rightarrow J = \begin{pmatrix} F_\theta & F_v \\ g_\theta & g_v \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -\cos \theta & -r \end{pmatrix}$$

$$\text{tr } J = -r, \quad \det J = \cos \theta$$

$$(\bar{\theta}, \bar{v}) = (0, 0): \text{tr } J = -r, \quad \det = 1 > 0 \Rightarrow \text{asy. stable}$$

$$(\bar{\theta}, \bar{v}) = (\pi, 0): \text{tr } J = -r, \quad \det = -1 < 0 \Rightarrow \text{unstable}$$

$$2. N_1' = r N_1 \cdot \left[1 - \frac{N_1}{K_1 + \alpha N_2} \right] = r N_1 - \frac{r N_1^2}{K_1 + \alpha N_2}$$

$$N_2' = r N_2 \cdot \left[1 - \frac{N_2}{K_2 + \beta N_1} \right] = r N_2 - \frac{r N_2^2}{K_2 + \beta N_1}$$

a) For both eqs, the population of the other species decreases the death rate (these are the negative terms in each eq) and the rate gets smaller as the other pop. increases - hence they are deriving mutual benefit from each other

$$b) N_1 = 0 \Rightarrow N_2 = 0 \quad \underline{\text{or}} \quad 1 - \frac{N_2}{K_2 + \beta N_1} = 0 \Rightarrow N_2 = K_2$$

$$N_1 = K_1 + \alpha N_2 \Rightarrow N_2 = 0 \quad \underline{\text{or}} \quad N_2 = K_2 + \beta (K_1 + \alpha N_2)$$

$$\Rightarrow N_2 = \frac{K_2 + \beta K_1}{1 - \alpha \beta} \quad \& \quad \alpha \beta < 1$$

∴ the steady-states are

$$(N_1, N_2) = (0, 0), (0, K_2), (K_1, 0), \text{ and}$$

$$\left(\frac{K_1 + \beta K_2}{1 - \alpha \beta}, \frac{K_2 + \beta K_1}{1 - \alpha \beta} \right)$$

c) this assumption guarantees that there is a steady-state with both values nonzero.

$$d) J = \begin{pmatrix} r \left(1 - \frac{N_1}{K_1 + \alpha N_2}\right) - \frac{r N_1}{K_1 + \alpha N_2} & r \frac{N_2 \alpha}{(K_1 + \alpha N_2)^2} \\ \frac{r N_2^2 \beta}{(K_2 + \beta N_1)^2} & r \left(1 - \frac{N_2}{K_2 + \beta N_1}\right) - \frac{r N_2}{(K_2 + \beta N_1)^2} \end{pmatrix}$$

$$= \begin{pmatrix} -r & \alpha r \\ \beta r & -r \end{pmatrix} \quad \leftarrow \frac{N_1}{K_1 + \alpha N_2} = 1 \quad \text{and} \quad \frac{N_2}{K_2 + \beta N_1} = 1$$

\Rightarrow

$$\lambda_1 = -2r \quad \text{and} \quad \det = r^2 - \alpha\beta r^2 = (1 - \alpha\beta)r^2 > 0$$

< 0

∞ steady-state is asy. stable

3. $x' = x [x(1-x) - y] \quad \mu > 0 \quad \text{and} \quad \mu > 0$
 $y' = k \left(x - \frac{1}{\mu}\right) y$

a) First note that the x' equation has multiple interpretations (depending how you write it). One way is

$$x' = \underbrace{x^2(1-x)}_{\substack{\text{for } x < 1 \text{ this} \\ \text{is the birth rate} \\ \text{but for } x > 1 \text{ it contributes} \\ \text{to the death rate}}} - \underbrace{xy}_{\substack{\text{death rate (usual} \\ \text{pred/prey} \\ \text{term)}}}$$

$$y' = \underbrace{-\frac{k}{\mu} y}_{\substack{\text{usual death} \\ \text{rate for} \\ \text{predator}}} + \underbrace{kxy}_{\substack{\text{usual birth rate for} \\ \text{predator}}}$$

b) $(x, y) = (\bar{x}, \bar{y}) \Rightarrow \bar{x} [\bar{x}(1-\bar{x}) - \bar{y}] = 0$
 $k \left(\bar{x} - \frac{1}{\mu}\right) \bar{y} = 0$

$$\bar{y} = 0 \Rightarrow \bar{x}^2(1-\bar{x}) = 0 \Rightarrow \bar{x} = 0, 1$$

$$\bar{x} = \frac{1}{\mu} \Rightarrow \bar{y} = \bar{x}(1-\bar{x}) = \frac{1}{\mu} \left(1 - \frac{1}{\mu}\right)$$

∞ steady-states are

$$(\bar{x}, \bar{y}) = (0, 0), (1, 0), \left(\frac{1}{\mu}, \frac{1 - \frac{1}{\mu}}{\mu}\right)$$

$$c) \quad \begin{aligned} f &= x^2(1-x) - xy \\ g &= k(x - \frac{1}{\mu})y \end{aligned}$$

$$J = \begin{pmatrix} 2x(1-x) - x^2 - y & -x \\ ky & k(x - \frac{1}{\mu}) \end{pmatrix}$$

$$(\bar{x}, \bar{y}) = (0, 0): \quad J = \begin{pmatrix} -1 & -1 \\ 0 & k(1 - \frac{1}{\mu}) \end{pmatrix}$$

$$t_1 = -1 + k(1 - \frac{1}{\mu}) \quad \det = -k(1 - \frac{1}{\mu})$$

so, $\mu > 1 \Rightarrow \det < 0$ and $\mu < 1 \Rightarrow \det > 0$ and $t_1 < 0$

∞ asy. stable if $\mu < 1$ and unstable if $\mu > 1$

$$(\bar{x}, \bar{y}) = \left(\frac{1}{\mu}, \frac{1 - \frac{1}{\mu}}{\mu}\right) \Rightarrow \quad J = \begin{pmatrix} \frac{1}{\mu}(1 - \frac{2}{\mu}) & -\frac{1}{\mu} \\ \frac{k}{\mu}(1 - \frac{1}{\mu}) & 0 \end{pmatrix}$$

$$t_1 = \frac{1}{\mu}(1 - \frac{2}{\mu}) \quad \text{and} \quad \det = \frac{k}{\mu^2}(1 - \frac{1}{\mu})$$

so, $\mu < 1 \Rightarrow \det < 0 \Rightarrow$ unstable

$1 < \mu < 2 \Rightarrow \det > 0$ and $t_1 < 0 \Rightarrow$ asy. stable

$\mu > 2 \Rightarrow t_1 > 0 \Rightarrow$ unstable

$$d) \quad (\bar{x}, \bar{y}) = (1, 0): \quad t_1^2 - 4\det = \left[-1 + k\left(1 - \frac{1}{\mu}\right)\right]^2 - 4 \cdot (-k) \left(1 - \frac{1}{\mu}\right) \\ = 1 > 0 \quad \mu = 1$$

∞ no Hopf bif.

$$(\bar{x}, \bar{y}) = \left(\frac{1}{\mu}, \frac{1 - \frac{1}{\mu}}{\mu}\right): \quad t_1^2 - 4\det = \frac{1}{\mu^2} \left(1 - \frac{2}{\mu}\right)^2 - \frac{4k}{\mu^2} \left(1 - \frac{1}{\mu}\right)$$

$\mu = 1 \Rightarrow$ no Hopf bif (see above)

$\mu = 2 \Rightarrow t_1^2 - 4\det = -4 \cdot \frac{k}{4} \cdot \frac{1}{2} < 0$

and $\frac{d}{d\mu} + 1 = \frac{-1}{\mu^2} \left(1 - \frac{2}{\mu}\right) + \frac{1}{\mu} \cdot \frac{2}{\mu^2}$ $\downarrow \mu=2$

$$= \frac{1}{4} > 0$$

\therefore there is a Hopf bif at $\mu=2$

Extra Credit

$$\begin{aligned} a) \quad S' &= \pi - \beta SZ - \delta S && \textcircled{1} \quad \textcircled{2} \\ Z' &= \beta SZ + \gamma R - \alpha SZ && \textcircled{1} \quad \textcircled{4} \quad \textcircled{3} \\ R' &= \delta S + \alpha SZ - \gamma R && \textcircled{2} \quad \textcircled{3} \quad \textcircled{4} \end{aligned}$$

① $S + Z \xrightarrow{\beta} ZZ$ } alive + zombie \rightarrow 2 zombies

② $S \xrightarrow{\delta} R$ } alive becomes dead

③ $S + Z \xrightarrow{\alpha} S + R$ } alive + zombie \rightarrow alive + dead

④ $R \xrightarrow{\gamma} Z$ } dead becomes zombie

b) There is no "really dead" state - which means a state the zombies can't come back from

One way to fix this is to replace ③ with



where $D \equiv$ really dead